Tensor Networks for Machine Learning

E.M. Stoudenmire May 2024 - Padua ETN School

Sample Codes

Quick demo – tensor ML is powerful!

Let's machine learn the following function into a tensor network:

40 Gaussians, random location, width, & height + a sharp step at 0.4

Today's Talk

Brief review of tensor networks

Why tensor networks for machine learning? Inspiration from DMRG.

Basis and amplitude encodings of data

Example applications

Future of tensor network machine learning

Tensors – Penrose Diagram Notation

 N -index tensor $=$ shape with N lines

$$
T^{s_1 s_2 s_3 \cdots s_N} = \underbrace{\begin{array}{c} s_1 s_2 s_3 s_4 & \cdots & s_N \\ \hline \rule{0mm}{3mm} & \rule{0mm}{3mm} & \rule{0mm}{3mm} \end{array}}
$$

Low-order examples:

Tensors – Penrose Diagram Notation

Joining wires means contraction:

We are familiar with tensors from quantum many-body

All values of *f* inside *s*¹ *s*² *s*³ *s*⁴ *s*⁵ *s*⁶ *f*(*s*1,*s*2,*s*3,*s*4,*s*5,*s*6) =

$$
f(1, 2, 2, 2, 1, 2) = \begin{array}{|c|c|c|c|}\n\hline\n1 & 2 & 2 & 1 & 2 \\
\hline\nL & 1 & L & L \\
\hline\nL & 2 & 2 & 1 & 2 \\
\hline\nL & 1 & L & L \\
\hline\nL & 2 & 2 & 1 & 2 \\
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\hline\nL & 2 & 2 & 1 & 2 \\
\hline\nL & 2 & 2 & 1 & 2 \\
\hline\nL & 2 & 2 &
$$

= 0.3 *f*(2, 2, 2, 2, 2, 1) = 2 2 2 2 2 1

$$
f(2, 1, 2, 2, 2, 2) = \begin{array}{|c|c|c|}\n\hline\n2 & 1 & 2 & 2 & 2 \\
\hline\n1 & 1 & 1 & 1 \\
\hline\n2 & 2 & 2 & 2 \\
\hline\n2 & 0 & 2 & 2\n\end{array}
$$

= 2.7 *f*(2, 1, 1, 2, 2, 2) = 2 1 1 2 2 2

Later we will see technique to encode continuous variable functions too

$$
f(x) \approx f(0.d_1d_2d_3d_4d_5d_6) = \begin{bmatrix} d_1 & d_2 & d_3 & d_4 & d_5 & d_6 \\ 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 \end{bmatrix}
$$

Why are tensors challenging?

Tensor with 50 indices would have

1,125,899,906,842,624 ~ 1015 parameters

Just as factorizing (SVD) a matrix reduces cost of memory and compute

χ is matrix rank

Result is a matrix product state or tensor train

Advantage if internal indices small, yet accuracy is good (small "bond dimension" or "rank"*χ*)

For large enough χ (= $2^{N/2}$), MPS can represent any tensor

Most algorithms require χ^3 computation, memory *χ*2

Can efficiently sum MPS in compressed form:

multiply by other networks:

and perfectly sample:

There are other tensor networks too,

with their own algorithms and degrees of expressive power

Power of tensor networks is algorithms

Seminal tensor network algorithm is DMRG (density matrix renormalization group)

$$
\min_{\psi} \frac{\langle \psi | H | \psi \rangle}{\langle \psi | \psi \rangle} = E_0
$$

Finds ground state and its energy

DMRG algorithm

Assume we can write *H* as a tensor network

DMRG algorithm

DMRG finds its ground state as an MPS tensor network

DMRG algorithm

Energy is

DMRG algorithm

DMRG algorithm

DMRG algorithm

DMRG uses an "alternating" strategy to optimize

DMRG algorithm

DMRG uses an "alternating" strategy to optimize

DMRG algorithm

DMRG uses an "alternating" strategy to optimize

DMRG algorithm

At each step, solve a "mini" diagonalization problem

DMRG algorithm

At each step, solve a "mini" diagonalization problem*

*technical note: for efficiency, frozen tensors are contracted in three groups, not exactly as shown above

DMRG algorithm

At each step, solve a "mini" diagonalization problem*

*technical note: for efficiency, frozen tensors are contracted in three groups, not exactly as shown above

DMRG algorithm

DMRG in action – solving Heisenberg chain

DMRG algorithm

DMRG in action – solving Heisenberg chain

FIG. 5. CPU time (seconds) for the Hubbard-Holstein model.

COMPOCH, USDOITIE, dIXIV.2403.00302 (2024) McCulloch, Osborne, arxiv:2403.00562 (2024)

Can we harness the power of tensor networks for machine learning?

Lightning review of machine learning concepts \neq

Sometimes have large "data set" up front:

Can divide into training / validation / test

Sometimes given no data, but can call a function:

```
distance\_from\_goal(position) \rightarrow number
```


Various "tasks" in machine learning:

• Supervised learning *predict labels for data, classify data*

Various "tasks" in machine learning:

• Unsupervised learning / generative modeling *recover distribution of data, or properties of that distribution (e.g."clusters")*

Various "tasks" in machine learning:

• Active learning *recover a function by querying at points*

In all cases, seek a model function with parameters

f θ $\left(\overrightarrow{x}\right)$ data input *x* model parameters *θ*

Optimize parameters *θ* until function accomplishes task

For example, in supervised learning, model is

$$
f_{\vec{\theta}}^{\ell}(\vec{x}) \qquad \ell = \text{label}
$$

 Θ ptimize parameters $\vec{\theta}$ until f^ℓ outputs maximum value when ℓ is the correct label of input \vec{x}

Three challenges for tensor networks:

• representation of data

• training algorithms

99999

• good problem selection

Three challenges for tensor networks:

• representation of data

• training algorithms

<u>9 9 9 9 9 9 </u>

• good problem selection

Representations of data

Say we are given a piece of data with *N* components

View as vector of length *N*

$$
\vec{x} = [x_1, x_2, x_3, \ldots, x_N]
$$

Representations of data

If data entries are integers, nothing else to do

$$
\vec{x} = [i_1, i_2, i_3, \dots, i_N] \qquad i_j \in \mathbb{Z}
$$

Just use tensor network as model:

Test your knowledge: what are parameters $\dot{\theta}$?

Representations of data

Say we are given a piece of data with *N* components

What about continuous entries? $x_i \in \mathbb{R}$

$$
\vec{x} = [x_1, x_2, x_3, \ldots, x_N]
$$

Representations of data

Two main encodings of continuous data into tensors

 $\vec{x} = [x_1, x_2, x_3, ..., x_N]$ … s_1 s_2 s_3 s_4 s_5 s_6 s_N Basis encoding **Amplitude encoding** *b*¹ *b*² *b*³ *b*⁴ *b*⁵ *b*⁶ *b*⁷ *b*⁸ $=x_b$

Representations of data

Basis encoding

For input input size *N*, use *N* indices (high dimensional) also known as "state encoding" or "product encoding"

Representations of data

Amplitude encoding

For input size *N*, log(*N*) indices (low dimensional)

Basis encoding

Map each pixel to a vector

Take (formal) outer product

$$
x_j \to \begin{bmatrix} \cos(\frac{\pi}{2}x_j) \\ \sin(\frac{\pi}{2}x_j) \end{bmatrix} \qquad \qquad \vec{x} \to \begin{bmatrix} \cos(\frac{\pi}{2}x_1) \\ \sin(\frac{\pi}{2}x_1) \end{bmatrix} \begin{bmatrix} \cos(\frac{\pi}{2}x_2) \\ \sin(\frac{\pi}{2}x_2) \end{bmatrix} \begin{bmatrix} \cos(\frac{\pi}{2}x_3) \\ \sin(\frac{\pi}{2}x_3) \end{bmatrix} \cdots
$$

Basis encoding

Another choice of "local feature map" is

$$
x_j \to \begin{bmatrix} 1 \\ x_j \end{bmatrix} \qquad \qquad \vec{x} \to \begin{bmatrix} 1 \\ x_1 \end{bmatrix} \begin{bmatrix} 1 \\ x_2 \end{bmatrix} \begin{bmatrix} 1 \\ x_3 \end{bmatrix} \cdots
$$

Can make into a function, or machine learning model, by contracting with a tensor

$$
f(x_1, x_2, ..., x_N) = \begin{bmatrix} 1 \\ x_1 \end{bmatrix} \begin{bmatrix} 1 \\ x_2 \end{bmatrix} \begin{bmatrix} 1 \\ x_3 \end{bmatrix} \begin{bmatrix} 1 \\ x_4 \end{bmatrix} \begin{bmatrix} 1 \\ x_5 \end{bmatrix} \begin{bmatrix} 1 \\ x_6 \end{bmatrix} \left(\frac{1}{x} \right)
$$

A very high-order polynomial

$$
f(x_1, x_2, ..., x_N) = \begin{bmatrix} 1 & 1 & 1 \ x_1 & 1 & 1 \ x_2 & 1 & 1 \ x_3 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \ x_2 & 1 \ x_3 \end{bmatrix} \begin{bmatrix} 1 & 1 \ x_3 & 1 \ x_4 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \ x_4 & 1 \ x_5 & 1 \ x_6 & 1 \end{bmatrix}
$$

= $W^{111111} + W^{211111}x_1 + W^{12111}x_2 + W^{112111}x_3 + \dots$
+ $W^{221111}x_1x_2 + W^{212111}x_1x_3 + W^{12211}x_2x_3 + \dots$
+ $W^{222222}x_1x_2x_3x_4x_5x_6$

 $=$?

Test your understanding: what function is this?

Test your understanding: what function is this?

W weight tensor

 $= 1 + x_1 x_2$

Test your understanding: what function is this?

$$
\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}
$$

$$
\begin{bmatrix} 1 \\ x_1 \\ x_2 \end{bmatrix} \begin{bmatrix} 1 \\ x_2 \\ x_3 \end{bmatrix} \begin{bmatrix} 1 \\ x_3 \\ x_4 \end{bmatrix} \begin{bmatrix} 1 \\ x_5 \\ x_6 \end{bmatrix} \begin{bmatrix} 1 \\ x_6 \\ x_6 \end{bmatrix}
$$

W weight tensor

 $=$?

Test your understanding: what function is this?

$$
\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}
$$

$$
\begin{bmatrix} 1 \\ x_1 \\ x_2 \end{bmatrix} \begin{bmatrix} 1 \\ x_2 \\ x_3 \end{bmatrix} \begin{bmatrix} 1 \\ x_3 \\ x_4 \end{bmatrix} \begin{bmatrix} 1 \\ x_5 \\ x_6 \end{bmatrix} \begin{bmatrix} 1 \\ x_6 \\ x_7 \end{bmatrix}
$$

W weight tensor

 $= x_1 x_2 x_3 x_4 x_5 x_6$

Test your understanding: what function is this?

\mathbf{R} 1 x_1 || 1 x_2 [] 1 x_3] 1 x_4 || 1 x_5][1 x_6 $\overline{}$ 1 1 \vert 1 1] [1 1] [1 1 \vert 1 1 \vert 1 1]

W weight tensor

 $=$?
Test your understanding: what function is this?

1 1 1 1 1 1 \mathbf{I} 1] [1] [1 \vert 1 \vert 1 \vert 1] 1 1 1 1 1 1 \mathbf{R} x_1 || x_2 [] x_3] x_4][x_5][x_6

W weight tensor

 $= (1 + x_1)(1 + x_2)(1 + x_3)(1 + x_4)(1 + x_5)(1 + x_6)$

Exponentially many weights in general

$$
f(x_1, x_2, ..., x_N) = \begin{bmatrix} 1 \\ x_1 \end{bmatrix} \begin{bmatrix} 1 \\ x_2 \end{bmatrix} \begin{bmatrix} 1 \\ x_3 \end{bmatrix} \begin{bmatrix} 1 \\ x_4 \end{bmatrix} \begin{bmatrix} 1 \\ x_5 \end{bmatrix} \begin{bmatrix} 1 \\ x_6 \end{bmatrix}
$$
 weight tensor

Use tensor network to make efficient

$$
f(x_1, x_2, \dots, x_N) = \bigcap_{\begin{bmatrix} 1 \\ x_1 \end{bmatrix} \begin{bmatrix} 1 \\ x_2 \end{bmatrix} \begin{bmatrix} 1 \\ x_3 \end{bmatrix} \begin{bmatrix} 1 \\ x_4 \end{bmatrix} \begin{bmatrix} 1 \\ x_5 \end{bmatrix} \begin{bmatrix} 1 \\ x_6 \end{bmatrix}
$$
 Weight MPS

Higher bond dimension χ = more representation power

W weight MPS

Train using alternating gradient descent

Could use favorite neural network or autodifferentiation framework (JAX, PyTorch, etc.)

Train using alternating gradient descent

$$
C = \frac{1}{N_T} \sum_{j=1}^{N_T} (f(\vec{x}_j) - y_j)^2
$$

Train using alternating gradient descent

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$$

Train using alternating gradient descent

$$
C = \frac{1}{N_T} \sum_{j=1}^{N_T} (f(\vec{x}_j) - y_j)^2
$$

Example: Supervised learning of MNIST handwriting

Train to 99.95% accuracy on 60,000 training images

Obtain 99.03% accuracy on 10,000 test images (only 97 incorrect) Stoudenmire, Schwab, arxiv:1605.05775

Example: Supervised learning of MNIST handwriting

 $\begin{smallmatrix} \mathop{ \mathcal{O} \end{smallmatrix}$ 11112117111111 22222222222220 33333333333333 55555555555555 66666666666666 999999999999999

Amplitude encoding

In this representation, indices do not correspond to different features.

Instead, indices "collectively" access each feature.

Let's see how this works...

Amplitude encoding

Say we have data vector *x*

$$
\vec{x} = [x_0, x_1, x_2, \dots, x_{N-1}]
$$
 (zero indexed)

$$
\begin{array}{c|cccc}\n0 & 0 & 0 & 0 & 0 & 0 \\
\hline\n0 & 0 & 0 & 0 & 0 \\
\hline\n0 & 0 & 0 & 0 & 0 \\
\hline\n0 & 0 & 0 & 0 & 0 \\
\hline\n0 & 0 & 0 & 0 & 0 \\
\hline\n0 & 0 & 0 & 0 & 0 \\
\hline\n0 & 0 & 0 & 0 & 0 \\
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\hline\n0 & 0 &
$$

Amplitude encoding

Say we have data vector *x*

$$
\vec{x} = [x_0, x_1, x_2, \dots, x_{N-1}]
$$
 (zero indexed)

$$
\begin{array}{c|cccc}\n0 & 0 & 0 & 0 & 0 & 0 & 1 \\
\hline\n & 1 & 1 & 1 & 1 & 1 \\
\hline\n & 1 & 1 & 1 & 1 & 1\n\end{array} = x_1
$$

Amplitude encoding

Say we have data vector *x*

$$
\vec{x} = [x_0, x_1, x_2, \dots, x_{N-1}]
$$
 (zero indexed)

$$
\begin{array}{c|cccc}\n0 & 0 & 0 & 0 & 0 & 1 & 0 \\
\hline\n0 & 0 & 0 & 0 & 1 & 0 \\
\hline\n0 & 0 & 0 & 0 & 1 & 0 \\
\hline\n0 & 0 & 0 & 0 & 1 & 0 \\
\hline\n0 & 0 & 0 & 0 & 1 & 0 \\
\hline\n0 & 0 & 0 & 0 & 0 & 0 \\
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\hline\n0 &
$$

Amplitude encoding

Say we have data vector *x*

$$
\vec{x} = [x_0, x_1, x_2, \dots, x_{N-1}]
$$
 (zero indexed)

$$
\begin{array}{c|cccc}\n0 & 0 & 0 & 0 & 0 & 1 & 1 \\
\hline\n & 1 & 1 & 1 & 1 \\
\hline\n & 1 & 1 & 1 & 1\n\end{array} = x_3
$$

Amplitude encoding

Say we have data vector *x*

$$
\vec{x} = [x_0, x_1, x_2, \dots, x_{N-1}]
$$
 (zero indexed)

$$
\begin{array}{c|cccc}\n0 & 0 & 0 & 0 & 1 & 0 & 0 \\
\hline\n & 1 & 1 & 1 & 1 & 1 \\
 & 1 & 1 & 1 & 1 & 1\n\end{array} = x_4
$$

Amplitude encoding

Say we have data vector *x*

$$
\vec{x} = [x_0, x_1, x_2, \dots, x_{N-1}]
$$
 (zero indexed)

$$
\begin{array}{c|cccc}\n0 & 0 & 0 & 0 & 1 & 0 & 1 \\
\hline\n & 1 & 1 & 1 & 1 & 1 \\
\hline\n & 1 & 1 & 1 & 1 & 1\n\end{array} = x_5
$$

Amplitude encoding

Say we have data vector *x*

$$
\vec{x} = [x_0, x_1, x_2, \dots, x_{N-1}]
$$
 (zero indexed)

$$
\begin{array}{c|cccc}\n1 & 1 & 1 & 1 & 1 & 1 \\
\hline\n1 & 1 & 1 & 1 & 1 \\
\hline\n\end{array} = x_{N-1}
$$

Amplitude encoding

Viewed as a quantum state, it is just

$$
\vec{x} = [x_0, x_1, x_2, \dots, x_{N-1}]
$$
 (zero indexed)
\n
$$
|\vec{x}\rangle = \sum_{i=0}^{2^n - 1} x_i |i\rangle
$$

Amplitude encoding

To make efficient, again factorize as MPS

Amplitude encoding

To make into a model, contract with weight MPS

Amplitude encoding

$$
f(\vec{x}) = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \leftarrow \vec{x}
$$

Since indices enumerate entries of \vec{x} one-by-one, it is just a 'linear classifier' in tensor form

$$
f(\vec{x}) = w_1 x_1 + w_2 x_2 + \dots + w_n x_n
$$

Not very powerful...

Amplitude encoding

Make more powerful by repeating ("stacking") data input

Now model contains linear + quadratic terms

$$
f(\vec{x}) = a + w_1 x_1 + \dots + w_{11}(x_1)^2 + w_{12} x_1 x_2 + \dots
$$

Application: Supervised learning of "Fashion-MNIST"

DILIP, LIU, SMITH, AND POLLMANN PHYSICAL REVIEW RESEARCH **4**, 043007 (2022) is not limited by the entanglement of the quantum state in the amplitude and basis amplitude and basis on codod data encoded data Use patches of

MATRIX-PRODUCT STATES Obtain 90% test chine learning, including the data-encoding scheme and the accuracy (!) using $\nu = 10$ accuracy (!) using $\chi=10$ 0.75 Accuracy (\sim χ class = 10) γ \boldsymbol{A} $\overline{\mathbf{1}}$ 4× 4 (112) $\overline{1}$

Dilip, Liu, Smith, Pollmann, PRR 4, 043007 (2022)

Application: Quantum Circuit Learning Models

Wright, Barratt, Green, et al., arxiv 2205.09768 (2022) ⁵

 $|0\rangle$ |
|} $|0\rangle$ $|\phi \rangle$ $|0\rangle$ $|0\rangle$ $|0\rangle$ Deterministic (no gradient, linear algebra) learning ĭ ⟨ l $|b\rangle$ MII Use "stacking" (inputting data multiple times) FIG. 3. Circuit Representation of MPS-encoded imto get higher-order functions

Let's do some brief "theory of tensor network machine learning"...

Mixing high-dimensional and low-dimensional encoding gives "universal approximation theorem" for tensor networks

Tensor entries arbitrary, so can store any function on exponentially fine continuum grid

Mixing high-dimensional and low-dimensional encoding gives "universal approximation theorem" for tensor networks

 $f(x_1, x_2, x_3, \ldots, x_N) \approx$

And any tensor is representable by MPS with large enough bond dimension *χ*

No explicit non-linearities, and yet true
Tensor network learning is a form of kernel learning

Yet training scales linearly with data set size

Does not use "kernel trick" which scales quadratically

The Future of Tensor Network Machine Learning

Continuum amplitude encoding

- Especially useful for continuous inputs to tensors
- For a function *f*, evaluate on fine grid of spacing 1/2*ⁿ*

 $\vec{f} = [f(0.0000), f(0.0001), f(0.0010), ..., f(0.1111)]$

One powerful technique is

Continuum amplitude encoding ("quantics tensor train")

Especially useful for continuous inputs to tensors

 $\sum_i A^i(x) B^i(y)$

Continuum amplitude encoding

For a function *f*, evaluate on fine grid of spacing 1/2*ⁿ*

 $\vec{f} = [f(0.0000), f(0.0001), f(0.0010), ..., f(0.1111)]$

Continuum amplitude encoding

For a function *f*, evaluate on fine grid of spacing 1/2*ⁿ*

$$
\vec{f} = [f(0.0000), f(0.0001), f(0.0010), ..., f(0.1111)]
$$

$$
\begin{array}{ccc}\nb_1 & b_2 & b_3 \\
\hline\n1 & 1 & 1 \\
\end{array}\n\qquad \qquad\n\begin{array}{ccc}\nb_n \\
\hline\n\end{array}\n\qquad\n\qquad\n\begin{array}{ccc}\nb_1 \\
\hline\n\end{array}\n\qquad f(0.b_1b_2b_3\cdots b_n)
$$

Continuum amplitude encoding

For a function *f*, evaluate on fine grid of spacing 1/2*ⁿ*

$$
\vec{f} = [f(0.0000), f(0.0001), f(0.0010), ..., f(0.1111)]
$$

0 . 0 0 0 0 0 0 0 0 = *f*(0.000000)

Continuum amplitude encoding

For a function *f*, evaluate on fine grid of spacing 1/2*ⁿ*

$$
\vec{f} = [f(0.0000), f(0.0001), f(0.0010), ..., f(0.1111)]
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Continuum amplitude encoding

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Continuum amplitude encoding

For a function *f*, evaluate on fine grid of spacing 1/2*ⁿ*

$$
\vec{f} = [f(0.0000), f(0.0001), f(0.0010), ..., f(0.1111)]
$$

- Continuum amplitude encoding
- It is a hierarchical representation of data

Continuum amplitude encoding

Continuum amplitude encoding

Continuum amplitude encoding

Continuum amplitude encoding

Key question: for a given *f*(*x*)

is F low-rank as a tensor network?

[1] Mazen Ali, Anthony Nouy, Constr Approx [2] Mazen Ali, Anthony Nouy, arxiv:2101.11932 [3] Chen, EMS, White, PRX Quantum, arxiv:2210.08468

Low rank for many cases

Tensor network low rank for:

- all smooth enough functions [1,2]
- functions with finite number of cusps or discontinuities [1,2]
- any Fourier transform of these [3]

Examples:

Works in 1D, 2D, ...

Continuum amplitude encoding

Payoff: can machine learn continuous functions

See [https://tensornetwork.org/functions](http://www.apple.com) for more details and key references

Future Direction #2: Tensor Train Recursive Sketching Algorithm

Talked a lot about representations

But real power is in algorithms

Tensor networks = high dimensional linear algebra

Should have deterministic algorithms (like QR, SVD, ...)

The "tensor train recursive sketching" (TTRS) algorithm estimates a probability distribution from samples

Very similar to "recursive SVD" for making MPS

But replace tensor with sum over training data

And apply "sketch" tensors to right-hand side

SVD of ϕ_1 recovers first MPS tensor

First tensor of distribution want to learn:

Then repeat recursively...

TTRS can accurately reconstruct probability distribution of *disordered* Ising chain

Provably optimal sketches known

For more details of TTRS algorithm, see following lecture and slides

[YouTube Link](https://youtu.be/Qbnek0yjZrg) (https://youtu.be/Qbnek0yjZrg) [Slides Link](https://itensor.org/miles/Trieste02TTRS.pdf) (https://itensor.org/miles/Trieste02TTRS.pdf)

References: Generative Modeling via Tensor Train Sketching, arxiv: 2202.11788 Generative Modeling via Hierarchical Tensor Sketching, arxiv: 2304.05305
Future Direction #3: Tensor Cross Interpolation Algorithm

The "tensor cross interpolation" (TCI) algorithm learns a function from calls to that function

It is an "active learning" algorithm

Invented and refined in following papers:

- I. Oseledets and E. Tyrtyshnikov, *TT-Cross Approximation for Multidimensional Arrays*, Linear Algebra Appl. 432, 70 (2010).
- D. V. Savostyanov, *Quasioptimality of Maximum- Volume Cross Interpolation of Tensors*, Linear Algebra Appl. 458, 217 (2014)
- S. Dolgov and D. Savostyanov, *Parallel Cross Interpolation* for High-Precision Calculation of High-Dimensional *Integ*rals, Comput. Phys. Commun. 246, 106869 (2020)
- Núnẽz Fernández, et al., *Learning Feynman Diagrams with Tensor Trains*, PRX 12, 041018 (2022)

Ivan Oseledets Dmitry Savostyanov Yuriel Núnẽz Fernández

Lifts the idea of the "interpolative decomposition" of a matrix to tensor networks

Given some matrix M, can reconstruct from a subset of columns

Leads to new MPS "gauge" with interpolation property

exact on 1,2,1,1,2,1 entry

Instead of viewing original tensor as an array, think of it as a callable function

Must be able to ask function for any element the TCI algorithm wants

We already saw yesterday the demo of learning

40 Gaussians, random location, width, & height + a sharp step at 0.4

Next demo: 2D function and optima

50 2D Gaussians, random location, width, & height

How were optima (global min and max) found?

Very interesting proposal called "TTOpt" [1]

Claim: TCI usually "encounters" global min and max

Alternatively can use MPS perfect sampling strategies [2]

[1] Sozykin, Chertkov, Schutski, Phan, Cichocki, Oseledets, TTOpt, NeurIPS (2022) [2] Chertkov, Ryzhakov, Novikov, Oseledets, arxiv:2209.14808

Fun paper using TTOpt to control a real robot arm! *

(a)

Figure 1. Solutions from TTGO for motion planning of a manipulator from a given initial configuration (white) to a final configuration (dark). The obtained joint angle trajectories result in different paths for the end.effector which are highlighted by dotted curves in different colors. The multimodality is clearly visible from these solutions.

TCI (= TT-Cross) algorithm

Figure 12. Real robot implementation of one of the TTGO
colutions for the pick and place task. The mation from the initial solutions for the pick-and-place task. The motion configuration to the final configuration (same as t configuration in this case) via the picking configuration and placing configuration is depicted. \sim 0.0 \sim je 1900.
... *3.6 TT-Cross* $T_{\rm eff}$ methods to find the TT decomposition of a term of a configuration to the final configuration (same as the initial also be adapted to this distribution. However, for simplicity \mathbf{r} solutions for the pick-and-place task. The motion from the initial can generate samples *x* ⇠ Pr by sampling from each of the conditional distributions in turn. Each conditions in turn. Each conditions in turn. Each conditional α

For more details of Tensor Cross algorithm, see following lecture and slides

[YouTube Link](https://youtu.be/PFijeMaRGUc) (https://youtu.be/PFijeMaRGUc)

[Slides Link](https://itensor.org/miles/Trieste03TCI.pdf) (https://itensor.org/miles/Trieste03TCI.pdf)

Tensor Network Machine Learning

Many other works I did not have time to cover e.g.

• Compressing neural network weights with tensor networks

Novikov et al., Advances in Neural Information Processing (2015) (arxiv:1509.06569) Garipov, Podoprikhin, Novikov, arxiv:1611.03214

• Tree networks of low-rank (CP rank) tensors

Chen, Barthel, arxiv:2305.19440

Outlook and Future Directions

Outlook

We saw a *framework* for machine learning using tensor networks

Goal of capturing power of tensor networks for physics but for broader applications

Outlook

Does it really deliver? It depends... (as of 2024)

For images / computer vision, promising but not yet competitive:

- tensor networks have lots of parameters (relatively)
- gradient descent is therefore slow
- but linear algebra algorithms much faster than gradient
- tensor networks are just linear algebra in high dimensions

Outlook

Does it really deliver? It depends... (as of 2024)

For low-to-medium dimensional functions, very powerful

Two novel algorithms for TN machine learning

What promise might they hold?